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Time : 1½ Hours**FIRST-TERM****MATHEMATICS****Subject Code**

H	4	7	5	4
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Total No. of Questions : 40 (Printed Pages : 16)**Maximum Marks : 40**

- INSTRUCTIONS :**
- (i) The question paper consists of 40 questions.
 - (ii) All questions are compulsory.
 - (iii) All questions are of Multiple Choice Type and carry *one* mark each.
 - (iv) For each question select only one correct option from the alternatives given.
 - (v) Use of calculator is not allowed.

1. The matrix $A = [a_{ij}]$ of order 2×2 whose elements are given by $a_{ij} = 2i - j$ is

(A) $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

(B) $\begin{bmatrix} 1 & 0 \\ 3 & 2 \end{bmatrix}$

(C) $\begin{bmatrix} 1 & 0 \\ 2 & 3 \end{bmatrix}$

(D) $\begin{bmatrix} 1 & 0 \\ -3 & 2 \end{bmatrix}$

2. Matrices A and B will be inverses of each other if and only if
- (A) $AB = BA$
 - (B) $AB = BA = O$
 - (C) $AB = O$ and $BA = I$
 - (D) $AB = BA = I$
3. If $A = \begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix}$, $A^2 - 5A$ is
- (A) an identity matrix
 - (B) a row matrix
 - (C) a scalar matrix
 - (D) a zero matrix
4. For a skew symmetric matrix, all the diagonal elements are
- (A) non-zero
 - (B) negative numbers
 - (C) positive numbers
 - (D) zero
5. If A is a square matrix such that $A^2 = I$, then $A^3 + (A + I)^2 - 9A - I^2 = \dots\dots\dots$.
- (A) $- 6A + I$
 - (B) $- 6A$
 - (C) $6A + I$
 - (D) $- 6A - I$

6. A, B, C are 3 matrices such that the order of A is 4×3 and the order of B is 4×5 and the order of C is 7×3 . Then the order of $(A^T B)^T C^T$ is

(A) 5×3

(B) 4×5

(C) 5×7

(D) 4×3

7. The value of $\begin{vmatrix} 1 & 1 & 1 \\ 11 & 10 & 9 \\ 101 & 100 & 99 \end{vmatrix}$ is

(A) 1

(B) -1

(C) 2

(D) 0

8. Given that A is a square matrix of order 3 and $|A| = -2$, then $|\text{Adj } A|$ is equal to

(A) 4

(B) -2

(C) -4

(D) 2

9. The determinant which is equal to $\begin{vmatrix} 4 & 3 \\ -5 & 1 \end{vmatrix}$ is

(A) $\begin{vmatrix} 3 & 1 \\ 2 & -1 \end{vmatrix}$

(B) $\begin{vmatrix} 6 & -5 \\ 5 & 1 \end{vmatrix}$

(C) $\begin{vmatrix} -6 & 5 \\ -5 & 1 \end{vmatrix}$

(D) $\begin{vmatrix} 3 & 4 \\ 1 & -5 \end{vmatrix}$

10. If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, such that $ad - bc \neq 0$, then $A^{-1} = \dots\dots\dots$

(A) $\frac{1}{ad - bc} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

(B) $\frac{1}{ad - bc} \begin{bmatrix} -d & b \\ c & -a \end{bmatrix}$

(C) $\frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

(D) $\frac{1}{ad - bc} \begin{bmatrix} d & b \\ c & a \end{bmatrix}$

11. If R is a relation in the set $\{a, b, c, d\}$ given by
 $R = \{(a, a), (b, b), (c, c), (d, d), (a, d), (a, b), (d, b)\}$, then
- (A) R is reflexive and symmetric but not transitive
 (B) R is reflexive and transitive but not symmetric
 (C) R is symmetric and transitive but not reflexive
 (D) R is an equivalence relation
12. The function $f: \mathbf{N} \rightarrow \mathbf{N}$ defined by $f(x) = x^3 + 12$ is
- (A) bijective
 (B) injective but not surjective
 (C) surjective but not injective
 (D) neither injective nor surjective
13. $*$ is a binary operation on \mathbf{R} defined by $a * b = a$, $a, b \in \mathbf{R}$, then
- (A) $*$ is commutative but not associative
 (B) $*$ is both commutative and associative
 (C) $*$ is neither commutative nor associative
 (D) $*$ is associative but not commutative
14. $f: \mathbf{R} \rightarrow \mathbf{R}$ is defined by $f(x) = \cos x$ and $g: \mathbf{R} \rightarrow \mathbf{R}$ is defined by $g(x) = x^2$.
 Then $(gof)(x) = \dots\dots\dots$
- (A) $\cos(x^2)$
 (B) $\cos^2 x$
 (C) $x^2 \cos x$
 (D) $x \cos x$

15. Let $\mathbf{R} - \left\{ \frac{-4}{3} \right\} \rightarrow \mathbf{R}$ be a function defined by $f(x) = \frac{4x}{3x+4}$, $x \neq \frac{-4}{3}$. The

inverse of f is the map $g : \text{Range of } f \rightarrow \mathbf{R} - \left\{ \frac{-4}{3} \right\}$ given by :

(A) $g(y) = \frac{3y}{3-4y}$

(B) $g(y) = \frac{4y}{3-4y}$

(C) $g(y) = \frac{3y}{4-3y}$

(D) $g(y) = \frac{4y}{4-3y}$

16. If f is a real function such that $f(x) = \frac{\sin^{-1} 3x}{4x}$, $x \neq 0$ is continuous at

$x = 0$, then $f(0) = \dots\dots\dots$.

(A) $\frac{4}{3}$

(B) $\frac{3}{4}$

(C) $\frac{-3}{4}$

(D) $\frac{-4}{3}$

17. The value of 'm' for which the real function f where

$$f(x) = \begin{cases} 5x - 4 & , 0 < x \leq 1 \\ 4x^2 + 3mx & , 1 < x < 2 \end{cases}$$

is continuous at every point in its domain is

(A) 7

(B) 0

(C) 1

(D) -1

18. To make the real function f continuous at $x = 2$, where

$$f(x) = \begin{cases} 2x & \text{if } x < 2 \\ k & \text{if } x = 2 \\ x^2 & \text{if } x > 2 \end{cases}$$

the value of k should be

- (A) 2
- (B) -2
- (C) 4
- (D) -4

19. $f : \mathbf{R} \rightarrow \mathbf{R}$ defined by

$$f(x) = \frac{a^x - a^{-x}}{x}, \quad x \neq 0$$
$$= 3k, \quad x = 0$$

is continuous at $x = 0$. Then $k = \dots\dots\dots$

- (A) $\frac{2}{3} \log a$
- (B) $\frac{-2}{3} \log a$
- (C) $\frac{3}{2} \log a$
- (D) $\frac{-3}{2} \log a$

20. If $y = x^2 \log x$, then $\frac{d^2y}{dx^2} = \dots\dots\dots$

(A) $2 \log x$

(B) $3 + 2 \log x$

(C) $2 + 2 \log x$

(D) $3 + \log x$

21. If $x + e^x = y + e^y$, then $\frac{dy}{dx} = \dots\dots\dots$

(A) $\frac{1 + e^x}{1 + e^y}$

(B) $\frac{1 + e^y}{1 + e^x}$

(C) $1 + e^x - e^y$

(D) $\frac{1 - e^x}{1 - e^y}$

22. If $y = e^{\log x^4}$, then $\frac{dy}{dx}$ at $x = -1$ is $\dots\dots\dots$

(A) e

(B) $-e$

(C) 4

(D) -4

23. If $x = a (1 - \cos t)$, $y = a (t + \sin t)$ where 't' is the parameter and 'a' is a constant, then $\left(\frac{dy}{dx}\right)_{t=\pi/2} = \dots\dots\dots$
- (A) -1
 (B) 1
 (C) $\pi/2$
 (D) $-\pi/2$
24. If $y = (\sin x)^{\cos x}$, then $\frac{dy}{dx} = \dots\dots\dots$
- (A) $(\sin x)^{\cos x} [\sin x \cot x - \sin x \log (\sin x)]$
 (B) $(\cos x)^{\sin x} [\cos x \cot x - \sin x \log (\sin x)]$
 (C) $(\sin x)^{\cos x} [\cos x \cot x - \sin x \log (\sin x)]$
 (D) $(\sin x)^{\cos x} [\cos x \cot x - \cos x \log (\sin x)]$
25. The derivative of $y = \sec^2 (x^3)$ with respect to x is $\dots\dots\dots$.
- (A) $6x^2 \sec^2 (x^3) \tan (x^3)$
 (B) $6x^2 \sec (x) \tan (x)$
 (C) $2x \sec (x^3) \tan (x^3)$
 (D) $6x^2 \sec (x^3) \tan (x^3)$
26. If $x \in [-1, 1]$, then $\sin^{-1}(-x) = \dots\dots\dots$.
- (A) $\sin^{-1} x$
 (B) $-\sin^{-1} x$
 (C) $\pi - \sin^{-1} x$
 (D) $\operatorname{cosec}^{-1} x$

27. $\tan^{-1} \frac{2}{11} + \tan^{-1} \frac{7}{24} = \dots\dots\dots$
- (A) $\tan^{-1}(1)$
- (B) $\tan^{-1}\left(\frac{1}{2}\right)$
- (C) $\tan^{-1}\left(\frac{3}{4}\right)$
- (D) $\tan^{-1}\left(\frac{2}{3}\right)$
28. If $y = \cos^{-1} x$, then
- (A) $x \in [-1, 1]; y \in [0, \pi]$
- (B) $x \in \mathbf{R}; y \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$
- (C) $x \in [-1, 1]; y \in \left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$
- (D) $x \in \mathbf{R} - [-1, 1]; y \in [0, \pi] - \left\{\frac{\pi}{2}\right\}$
29. The value of $\sec^2 \left[\tan^{-1} \left(\frac{5}{11} \right) \right]$ is
- (A) $\frac{25}{121}$
- (B) $\frac{96}{121}$
- (C) $\frac{146}{121}$
- (D) $\frac{121}{146}$

30. The value of p for which the vectors $\vec{a} = 3\hat{i} + 2\hat{j} + 9\hat{k}$ and $\vec{b} = \hat{i} + p\hat{j} + 3\hat{k}$ are parallel vectors is

(A) $\frac{2}{3}$

(B) $\frac{3}{2}$

(C) 2

(D) 3

31. If \vec{a} and \vec{b} are two unit vectors and θ is the angle between them, then

$\frac{\vec{a} + \vec{b}}{|\vec{a} + \vec{b}|}$ is a unit vector if $\theta = \dots\dots\dots$

(A) $\frac{\pi}{4}$

(B) $\frac{\pi}{3}$

(C) $\frac{\pi}{2}$

(D) $\frac{2\pi}{3}$

32. If \hat{i}, \hat{j} and \hat{k} are the three unit vectors, then the vector represented by

$$(\hat{i} \times \hat{j}) \times \hat{i} + (\hat{j} \times \hat{k}) \times \hat{j} + (\hat{k} \times \hat{i}) \times \hat{k} = \dots\dots\dots$$

(A) $\hat{i} + \hat{j} + \hat{k}$

(B) $\hat{i} - \hat{j} + \hat{k}$

(C) $\hat{i} + \hat{j} - \hat{k}$

(D) $\hat{i} - \hat{j} - \hat{k}$

33. The value of λ so that the vectors $\vec{a} = 2\hat{i} - \hat{j} + \hat{k}$, $\vec{b} = \hat{i} + 2\hat{j} - 3\hat{k}$, $\vec{c} = 3\hat{i} + \lambda\hat{j} + 5\hat{k}$ are coplanar is
- (A) -1
 (B) -2
 (C) -3
 (D) -4
34. Let \vec{r} be the position vector of an arbitrary point $p(x, y, z)$. The Cartesian form of the equation of the line passing through two points (x_1, y_1, z_1) and (x_2, y_2, z_2) is
- (A) $\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1}$
 (B) $\frac{x - x_1}{x_2 + x_1} = \frac{y - y_1}{y_2 + y_1} = \frac{z - z_1}{z_2 + z_1}$
 (C) $\frac{x + x_1}{x_2 + x_1} = \frac{y + y_1}{y_2 + y_1} = \frac{z + z_1}{z_2 + z_1}$
 (D) $\frac{x + x_1}{x_2 - x_1} = \frac{y + y_1}{y_2 - y_1} = \frac{z + z_1}{z_2 - z_1}$
35. The line $\frac{x - x_1}{a} = \frac{y - y_1}{b} = \frac{z - z_1}{c}$ is at right angles to the plane $Ax + By + Cz + D = 0$ if
- (A) $aA + bB + cC = 0$
 (B) $aA + bB + cC = 1$
 (C) $aA = bB = cC$
 (D) $\frac{a}{A} = \frac{b}{B} = \frac{c}{C}$

36. The distance of the plane $2x + 3y - 6z + 2 = 0$ from the origin is
- (A) 2
- (B) 14
- (C) $\frac{2}{7}$
- (D) $\frac{2}{\sqrt{23}}$
37. The equation of the plane passing through the intersection of the planes $x + 2y - 5z + 1 = 0$ and $2x - y + 3z - 11 = 0$ and also through the origin is
- (A) $13x + 21y - 52z = 0$
- (B) $13x - 21y - 52z = 0$
- (C) $13x + 21y + 52z = 0$
- (D) $13x + 21y - 52z = \frac{1}{11}$
38. The direction cosines of the normal to the plane $2x + 3y - z = 5$ are :
- (A) 2, 3, -1
- (B) $\frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}}, \frac{-1}{\sqrt{14}}$
- (C) 2, 3, 1
- (D) $\frac{2}{\sqrt{14}}, \frac{3}{\sqrt{14}}, \frac{1}{\sqrt{14}}$

39. The angle between the line $\vec{r} = (\hat{i} + 2\hat{j} - \hat{k}) + \lambda(\hat{i} - \hat{j} + \hat{k})$ and the plane $\vec{r} \cdot (2\hat{i} - \hat{j} + \hat{k}) = 6$ is

(A) $\sin^{-1}\left(\frac{2\sqrt{2}}{3}\right)$

(B) $\sin^{-1}\left(\frac{\sqrt{2}}{3}\right)$

(C) $\cos^{-1}\left(\frac{2}{3}\right)$

(D) $\sin^{-1}\left(\frac{1}{3}\right)$

40. The equation of the plane through the point $(-1, -1, 1)$ which is parallel to the plane $\vec{r} \cdot (\hat{i} + \hat{j} + \hat{k}) = 0$ is

(A) $\vec{r} \cdot (\hat{i} + \hat{j} + \hat{k}) + 1 = 0$

(B) $\vec{r} \cdot (\hat{i} + \hat{j} + \hat{k}) - 1 = 0$

(C) $\vec{r} \cdot (\hat{i} + \hat{j} + \hat{k}) + 3 = 0$

(D) $\vec{r} \cdot (\hat{i} + \hat{j} + \hat{k}) - 3 = 0$

Space For Rough Work

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